

# SREE SOWDAMBIKA COLLEGE OF ENGINEERNG CHETTIKURICHI (PO), ARUPPUKOTTAI – 626134 DEPARTMENT OF MECHANICAL ENGINEERING COURSE PLAN

Date:24/12/22

Doc.Ref:2.2.10/2

## Name of the Course Instructor: U.RAJKUMAR

Class: III Year

Course Code & Name: ME8594&DYNAMICS OF MACHINES Semester: V

VISION of SSCE	MISSION of SSCE				
To strive continuously for excellence in education,	To develop high quality technical education				
research, technology and interdisciplinary collaboration to meet the changing needs of the	through research and innovation by adapting the students to changing technological				
society.	environment with the highest ethical values.				

DEPARTMENT VISION transform the students from rural atmosphere to global scenario and make them to be a committed technocrat with ethical values.	<ul> <li>DEPARTMENT MISSION</li> <li>To enrich the skill sets of the students for sustaining their position in the global job Market.</li> </ul>
	• To install professional ethical practices in the minds of the students.
	• To encourage them to get adapted for the latest virtual learning.
	• To provide opportunities to the students to exhibit leadership, professionalism, Teamwork and effective communication skills.

#### **Department of Mechanical Engineering**

#### Programme Educational Objectives (PEOs)

The Program Educational Objectives of the Mechanical Engineering Degree Program are to impart Knowledge, Skill and Attitude on the graduates to:

PEO-1	Imparting Knowledge	Have a successful career in Mechanical Engineering and allied industries.						
PEO-2	Multi-discipline	Have expertise in the areas of Design, Thermal,						
PEO-3	Research Skill	Contribute towards technological development through academic research and industrial practices.						
PEO-4	Managerial Skill	Practice their profession with good communication, leadership, ethics and social responsibility.						
PEO-5	Life-long learning	Graduates will adapt to evolving technologies through life- long learning.						

#### Programme Outcomes (POs)

The Programme Outcomes of the B.E. Mechanical Engineering program

PO-1	Engineering knowledge	Apply the knowledge of mathematics, science, and basic engineering fundamentals to the solution of complex engineering problems in the major areas of Mechanical Engineering.
PO-2	Problem analysis	An ability to identify, formulates, and solve complex engineering problems. With high degree of competence.
PO-3	Design/developmen t of solutions	An ability to design mechanical systems, component, or a process to meet desired needs within the realistic constraints such as environmental, social, political and economic sustainability.
PO-4	Conduct investigations of complex problems	An ability to design and conduct experiments, as well as to analyze and interpret data obtained through those experiments.
PO-5	Modern tool usage	Create and apply appropriate techniques, resources, and modern engineering tools for executing engineering activities.

PO-6	The engineer and society	Apply reasoning of the societal, safety issues and the consequent responsibilities relevant to engineering practice.
PO-7	Environment and sustainability	The broad education is necessary to understand the impact of engineering solutions in a global, economic, environmental, and societal context.
PO-8	Ethics	Apply ethical principles and commit to professional ethics, responsibilities and norms of engineering practice.
PO-9	Individual and team work	Function effectively as an individual, and as a member or leader in diverse teams in multi-disciplinary settings.
PO-10	Communication	Communicate effectively to the engineering community and the outside world And also to write effective reports & presentation
PO-11	Project management and finance	Understand engineering and management principles and apply them to handle projects in multi-disciplinary environments.
PO-12	Life-long learning	Recognize the need for life-long learning and apply in the context of technological change.

**Programme Specific Outcomes (PSOs)** The graduates of Bachelor of Engineering in Mechanical Engineering Programme will be able to:

PSO-1	Basic Engineering Knowledge	Apply their knowledge in the domain of Thermal, Design, Manufacturing and Industrial engineering to solve engineering problem utilizing advanced technology with the help of modern CAD/CAM tools,				
PSO-2	Managerial Skill An ability to build the nation, by imparting technological managerial skills to become Technocrats and Entrepreneur attitude of developing new concepts on emerging fields an advanced education					
PSO-3	Research Skill	Ability to apply the knowledge to provide optimized solution by applying new ideas and innovation in research gaps of various mechanical engineering domain				

#### ME8594

#### **DYNAMICS OF MACHINES**

## **UNIT I FORCE ANALYSIS 12**

Dynamic force analysis – Inertia force and Inertia torque– D Alembert's principle –Dynamic Analysis in reciprocating engines – Gas forces – Inertia effect of connecting rod– Bearing loads – Crank shaft torque – Turning moment diagrams –Fly Wheels – Flywheels of punching presses- Dynamics of Cam- follower mechanism.

## **UNIT II BALANCING 12**

Static and dynamic balancing – Balancing of rotating masses – Balancing a single cylinder engine – Balancing of Multi-cylinder inline, V-engines – Partial balancing in engines – Balancing of linkages – Balancing machines-Field balancing of discs and rotors.

#### **UNIT III FREE VIBRATION 12**

Basic features of vibratory systems – Degrees of freedom – single degree of freedom – Free vibration– Equations of motion – Natural frequency – Types of Damping – Damped vibration– Torsional vibration of shaft – Critical speeds of shafts – Torsional vibration – Two and three rotor torsional systems.

## **UNIT IV FORCED VIBRATION 12**

Response of one degree freedom systems to periodic forcing – Harmonic disturbances – Disturbance caused by unbalance – Support motion –transmissibility – Vibration isolation vibration measurement.

## **UNIT V MECHANISM FOR CONTROL 12**

Governors – Types – Centrifugal governors – Gravity controlled and spring controlled centrifugal governors – Characteristics – Effect of friction – Controlling force curves. Gyroscopes –Gyroscopic forces and torques – Gyroscopic stabilization – Gyroscopic effects in Automobiles, ships and airplanes.

#### *TOTAL: 60 PERIODS* COURSE OBJECTIVES:

1. To understand the force-motion relationship in components subjected to external forces and analysis of standard mechanisms.

2. To understand the undesirable effects of unbalances resulting from prescribed motions in mechanism.

3. To understand the effect of Dynamics of undesirable vibrations.

4. To understand the principles in mechanisms used for speed control and stability control.

# LESSON PLAN

Lect	Syllabus topics	No. of	Cumulati	Teac	hing	Page no.						
NO.	hour ve period Methodology required Used					T1	R1	R2				
	UNIT I- FORCE ANALYSIS											
1	Turning moment diagram of flywheel: fluctuation of energy, coefficient of fluctuation of energy, numerical examples	2	2	BB	Z-A	1						
2	Flywheel: energy stored in a flywheel, dimensions of the flywheel rim, flywheel and punching press. Numerical example	2	4	BB	MM	12						
3	Numerical examples on flywheel	3	7	BB	MM	28						
4	partial balancing of multi-cylinder engine, numerical problems.	3	10	BB	MM	32						
5	Dynamic force analysis – Inertia force and Inertia torque	2	12	BB	RP	135						
6	Dynamics of Cam- follower mechanism.	3	13	BB	CL	36						
7.	Bearing loads – Crank shaft torque	3	16	BB	GD	52						
	UNIT II- <b>B</b> A	ALANCIN	G									
8.	Static and dynamic balancing, balancing of reciprocating mass, partial balancing of single cylinder engine, numerical examples	4	20	BB	MM	66						
9	Balancing of single revolving mass in same plane, balancing of several revolving masses in same plane, several rotating masses in different plane.	4	24	BB	MM	75						
10	Numerical problems on revolving masses.	2	26	BB	MM	79						
11	Direct and reverse crank method of balancing, numerical problems.	2	28	BB	RP	80						
12	Balancing machines-Field balancing of discs and rotors.	2	30	BB	CL	84						
13.	Balancing a single cylinder engine	3	33	BB	GD	88						
	UNIT III -FREE VIBRATION											
14.	Vibration: Introduction to vibration, causes of vibration, elimination of vibration, types of vibration	2	35	PPT	CL	90						
15.	longitudinal, transverse, torsional	2	37	BB	ZA	94						
16.	definition of terminology like natural frequency, amplitude , time	1	38	BB	FP	99						

	period							
	Calculation of natural frequency of	2			MM			
	undamped single degree of							
17	freedom system by Newton's 2nd		40	PPT		109		
	Law, D-Alembert's principle and							
	energy method							
	Basic features of vibratory systems	2		BB	GD			
18	<ul> <li>Degrees of freedom – single</li> </ul>		42			125		
	degree of freedom							
	vibration– Equations of motion –	2		BB	CL			
19	Natural frequency – Types of		44			145		
	Damping							
•	Two and three	2	1.6	DDT	FP	1.40		
20.	rotor torsional systems.		46	PPT		149		
					1			
	UNIT IV-FO	RCED V	IBRATIC	)N				
	Response of one degree freedom	1		BB	ММ			
21	systems to periodic forcing	1	47	DD	IVIIVI	158		
	systems to periodic forcing	2		DD	CD			
22	Harmonic disturbances	2	49	ВВ	GD	168		
23	Disturbance caused by unbalance	2	51	PPT	CL	188		
24	Support motion –transmissibility	1	52	BB	FP	200		
25	Vibration isolation	2	54	BB	RP	220		
	vibration	- 1			MM	254		
26	vioration	1	55	DDT	IVIIVI	254		
20	measurement.		55	111				
	UNIT V- MECH	ANISM FO	DR CONTR	ROL		1		
	UNIT V- MECH	ANISM FO	OR CONTR	ROL	1	I		
	UNIT V- MECH	ANISM FC	OR CONTR	ROL			1	
27	UNIT V- MECH	ANISM FC	DR CONTR	ROL BB	MM	259		
27	UNIT V- MECH Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems	ANISM FC	DR CONTE	ROL BB	MM	259		
27	UNIT V- MECH Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on	ANISM FC	57	ROL BB BB	MM	259		
27 28	UNIT V- MECH Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems.	<b>ANISM FC</b> 2 3	<b>DR CONTH</b> 57 60	BB BB	MM GD	259 280		
27 28	UNIT V- MECH Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems. Stability of 4-wheel automobile,	<b>ANISM FC</b> 2 3 2	<b>DR CONTE</b> 57 60	BB BB	MM GD CL	259 280		
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27 28 29	UNIT V- MECH. Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems. Stability of 4-wheel automobile, numerical problems Stability of two wheel vehicle,	2 2 3 2 1	57 60 32	ROL BB BB PPT BB	MM GD CL FP	259 280 300		
27 28 29 30	UNIT V- MECH. Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems. Stability of 4-wheel automobile, numerical problems Stability of two wheel vehicle, numerical problems	2 2 3 2 1	<b>DR CONTE</b> 57 60 32 63	ROL BB BB PPT BB	MM GD CL FP	259 280 300 320		
27 28 29 30	UNIT V- MECH Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems. Stability of 4-wheel automobile, numerical problems Stability of two wheel vehicle, numerical problems Effect of gyroscopic couple on naval	ANISM FC 2 3 2 1 2	57 60 32 63 65	BB BB PPT BB BB	MM GD CL FP RP	259 280 300 320		
27 28 29 30 31	UNIT V- MECH. Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems. Stability of 4-wheel automobile, numerical problems Stability of two wheel vehicle, numerical problems Effect of gyroscopic couple on naval ship, numerical problems.	ANISM FC 2 3 2 1 2	<b>DR CONTE</b> 57 60 32 63 65	BB BB PPT BB BB	MM GD CL FP RP	259 280 300 320 345		
27 28 29 30 31 32	UNIT V- MECH. Gyroscope: angular velocity, angular acceleration, gyroscopic couple, numerical problems Effect of gyroscopic couple on bearings, numerical problems. Stability of 4-wheel automobile, numerical problems Stability of two wheel vehicle, numerical problems Effect of gyroscopic couple on naval ship, numerical problems. Effect of gyroscopic couple on	ANISM FC 2 3 2 1 2 2	ST         60           32         63           65         67	ROL BB BB PPT BB BB BB	MM GD CL FP RP MM	259 280 300 320 345 368		
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# **Course Assessment Matrix**

Course Outcomes	PO1	PO2	PO3	PO4	PO 5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1													1		
CO2			2												
CO3		2													
CO4			2												
CO5	3														

Course Outcome	Skill	РО	Bloom's	Assessing Tools
Co1- Clear understanding the external forces and analysis of standard mechanisms	Remember/ Understand	Po3,pso1	L1/L2	
Co2- To apply Equations of motion Solve the three and three rotations problmes	Apply	Po1	L2	IAT Exam, Assignment and class test
Co3- Analyze and distinguish Balancing of Multi-cylinder inline, V-engines ,Partial balancing in engines	Analyse	Po2	L3	
Co4- To do investigation on the speed and lift of the governor and estimate the gyroscopic effect on automobiles, ships and airplanes.	Investigation	Po3,pso2	L4	



# SREE SOWDAMBIKA COLLEGE OF ENGINEERNG CHETTIKURICHI (PO), ARUPPUKOTTAI – 626134 DEPARTMENT OF MECHANICAL ENGINEERING COURSE PLAN

Doc.Ref:2.2.10/3

Date:

	CO1	CO2	CO 3	CO4	CO5	JUSTIFICATION
PO1				2		Students Using their research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions. As a reason for that Course Outcome 4 is strongly mapped with Programme Outcome 4.
PO2		2			3	Students will able to apply reasoning of the societal, safety issues and the consequent responsibilities relevant to engineering practice based on this relevance Course Outcome 2 is strongly mapped with Programme Outcome 1.
PO3			2			Students can analyze and understand the impact of Management principles in the environment and exhibit the knowledge for sustainable development of the society because of this Course Outcome 3 is strongly mapped on Programme Outcome 2
P04						Case study gives more confident level to students can gains an ability to function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings based on this outcome CO4 is moderately mapped with PO9.
PO5						dents acquires an ability to Communicate effectively on management related activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions. This outcome slightly mapped with CO3 and moderately mapped with CO4 because case studies given to students for the improvement of their communication skills.
PSO1	1					Students have a need for life-long learning and apply in the context of technological change this was obtained from course outcome 1 in the similar way CO1 is slightly mapped with PSO1.